

# CODING TIPS

## Lecture Notes

BM 531

Numerical Methods and C/C++ Programming

Ahmet Ademoglu, *PhD*

Bogazici University

Institute of Biomedical Engineering

# Rules for efficient C Coding

```
/* Bad Code */
sum[i]=0.;
for (j=1; j<100; j++)
sum[i]+=a[i][j];
sum[i]+=temp;

for (i=1; i<100; i++)
a[i][7]=c;
/* rightmost index varies most rapidly */

for (i=1; i<100; i++){
a=b*x*y*z;
c=d*y*z*x;
e=x*y+f;
g=h*y*x+z;
}
sum=0.;
for (i=1; i<100; i++)
sum+=fact*a[i];

double x[100],y[100];
for (i=0; i<100; i++){
x[i]*=i;
y[i]=x[i]/2.;
}

/* Good Code */
for (j=1,temp=0.; j<100; j++)
temp+=a[i][j];

for (i=1; i<100; i++)
a[7][i]=c;

for (i=1; i<100; i++){
a=b*(x*y*z);
c=d*(x*y*z);
e=(x*y)+f;
g=h*(x*y)+z;
}
sum=0.;
for (i=1; i<100; i++)
sum+=a[i];
sum*=fact;

double x[100],y[100],c;
for (i=0, c=0.; i<100; i++){
x[i]*=c;
y[i]=0.5*x[i];
c+=1.;
}
```

# Calling C Routines from MATLAB-mex Compilation

```
void shell(double **r, int q, double **s, int N, double **H)
/* THIS is a routine to be called from the MATLAB environment */
/* shell.c calculates the electric potential for the 4 shell spherical model */
/* r is a 2 d array with q by 3 */
/* q is the number of dipoles */
/* s is the 2 d array with N by 3 */
/* N is the number of electrodes */
/* H is the potential field matrix with */
/* N by 3*q */
/* mex file for shell.c */
/* Usage: H=matshell[r,s]; */
/* Will be stored in matshell.c */
#include "\MATLAB6p5\extern\include\mex.h"
#include "\MATLAB6p5\extern\include\matrix.h"
#include "shell.c"
void mexFunction(int nlhs, mxArray *plhs[], int nrhs, const mxArray *prhs[]){
int i,j,k,q,N;
double **r,**s,**H,*data1,*data2;
if (nrhs!=2){
mexErrMsgTxt("2 input arguments needed"); }
if (nlhs>1){
mexErrMsgTxt("1 output argument needed"); }
q=mxGetNumberOfElements(prh[0])/3;
/* get the number of dipoles from r which is Number of Dipoles X 3 */
N=mxGetNumberOfElements(prh[1])/3;
/* get the number of electrodes from s which is Number of electrodes X 3 */
```



```

r=(double **) mxMalloc(q*sizeof(double));
for (i=0;i<q;i++)
r[i]=(double *) mxMalloc(3*sizeof(double));
data1=mxGetPr(prh[0]);
for (k=0,j=0;j<3;j++)
for (i=0;i<q;i++,k++)
r[i][j]=data1[k];
s=(double **) mxMalloc(N*sizeof(double));
for (i=0;i<q;i++)
s[i]=(double *) mxMalloc(3*sizeof(double));
data1=mxGetPr(prhs[1]);
for (k=0,j=0;j<3;j++)
for (i=0;i<N;i++,k++)
s[i][j]=data1[k];
H=(double **) mxMalloc(N*sizeof(double));
for (i=0;i<q;i++)
H[i]=(double *) mxMalloc(q*3*sizeof(double));
shell(r,q,s,N,H);
plhs[0]=mxCreateDoubleMatrix(N,3*q,mxREAL);
data2=(double *) mxMalloc(N*3*q*sizeof(double));
for (k=0,j=0;j<(3*q);j++)
for (i=0;i<N;i++,k++)
data2[k]=H[i][j];
mxSetPr(plhs[0],data2);
}

```

#### WARNING!

mex codes given in this lecture are developed using Visual studio C compiler under Matlab Version 6.5. For other compilers and/or later versions of Matlab, necessary updates must be done for proper operation. See relevant Matlab documentation for mex compilation.



# More Efficient C Coding for MATLAB-mex Compilation

```
void shell(double *r, int q, double *s, int N, double *H)
/* This is a routine to be called from the MATLAB environment */
/* shell.c calculates the electric potential for the 4 shell spherical model */
/* r is a 1 d array with length q*3 */
/* q is the number of dipoles */
/* s is the 1 d array with length N*3 */
/* N is the number of electrodes */
/* H is the potential field vector with length N*3*q */
/* mex file for shell.c */
/* Usage: H=matshell[r,s]; */
/* Will be stored in matshell.c */
#include "\MATLAB6p5\extern\include\mex.h"
#include "\MATLAB6p5\extern\include\matrix.h"
#include "shell.c"
void mexFunction(int nlhs, mxArray *plhs[], int nrhs, const mxArray *prhs[]){
int i,j,k,q,N;
double *r,*s,*H;
if (nrhs!=2){ mexErrMsgTxt("2 input arguments needed"); }
if (nlhs>1){ mexErrMsgTxt("1 output argument needed"); }
q=mxGetNumberOfElements(prh[0])/3;
/* get the number of dipoles from r which is Number of Dipoles X 3 */
N=mxGetNumberOfElements(prh[1])/3;
/* get the number of electrodes from s which is Number of electrodes X 3 */
r=mxGetPr(prh[0]); s=mxGetPr(prhs[1]);
H=(double *) mxMalloc(N*3*q*sizeof(double));
shell(r,q,s,N,H);
plhs[0]=mxCreateDoubleMatrix(N,3*q,mxREAL); mxSetPr(plhs[0],H);
}
```

# Passing Arrays to Numerical Recipes Routines

## Numerical Recipes Routine for LU BACK SUBSTITUTION

```
void lubksb(a,n,indx,b)
double **a,b[];
int n,*indx;
```

Array addressing in NR is from 1 to N.

```
/* For arrays passed to NR routines allocation is done as follows */
int main(){
double **Matrix;
double *Vector;
int *Index;
Matrix = (double **) malloc(10*sizeof(double*));
Matrix--;
for (i=1;i<=10;i++)
Matrix[i]= (double *) malloc(10*sizeof(double));

Vector = (double *) malloc(10*sizeof(double));
Vector--;
Index = (int *) malloc(10,sizeof(int));
Index--;
return 0;
}
```

lubksb can be called from the main program as

```
lubksb(Matrix,10,Index,Vector);
```

